

Moment of inertia



System of particles and rotation

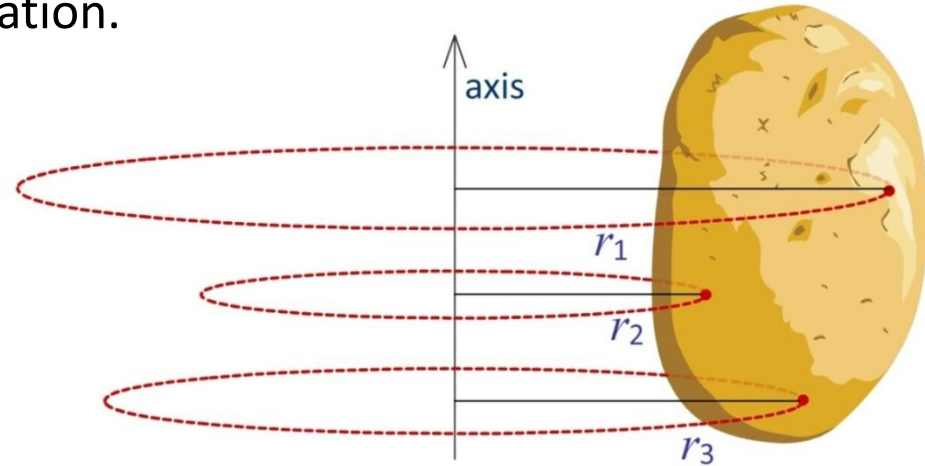
Moment of inertia (I)

It is defined as the sum of product of mass of each particle and square of its perpendicular distance from the axis of rotation.

$$I = \sum m r^2$$

$$I = \int dm r^2$$

SI unit : kg m^2



Rotational kinetic energy of the system is given by

$$KE = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_3 v_3^2 \dots$$

Using $v = r\omega$ (ω is constant)

$$KE = \frac{1}{2} m_1 r_1^2 \omega^2 + \frac{1}{2} m_2 r_2^2 \omega^2 + \frac{1}{2} m_3 r_3^2 \omega^2 \dots$$

$$KE = \frac{1}{2} \left[m_1 r_1^2 + m_2 r_2^2 + m_3 r_3^2 \dots \right] \omega^2$$

Representing the quantity in the square brackets I

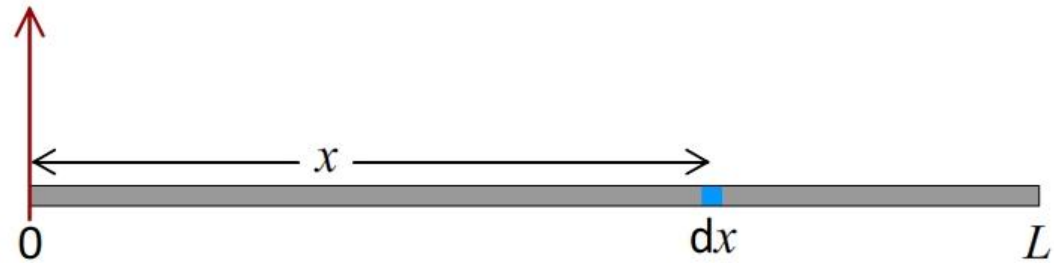
$$KE = \frac{1}{2} I \omega^2$$

System of particles and rotation

Moment of inertia of a thin rod about an axis passing through one of its ends & perpendicular to its length

Let mass of the rod be M and its length be L .

Consider a small segment of mass dm at a distance x from the axis of rotation.



Moment of inertia due to this segment is

$$dI = dm x^2$$

$$dI = \frac{M}{L} dx x^2$$

Total moment of inertia is given by

$$I = \int_i^f dm r^2$$

$$I = \int_0^L \frac{M}{L} x^2 dx$$

$$I = \frac{M}{L} \int_0^L x^2 dx$$

$$I = \frac{M}{L} \left[\frac{x^3}{3} \right]_0^L$$

$$I = \frac{M}{L} \left[\frac{L^3}{3} - 0 \right]$$

$$I = \frac{M}{L} \left[\frac{L^3}{3} \right]$$

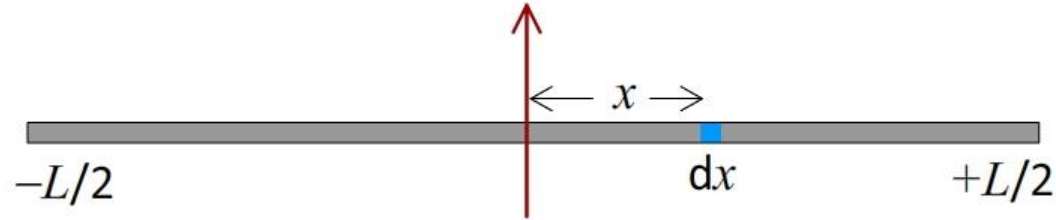
$$I = \frac{ML^2}{3}$$

System of particles and rotation

Moment of inertia of a thin rod about an axis passing through its centre and perpendicular to its length

Let mass of the rod be M and its length be L .

Consider a small segment of mass dm at a distance x from the axis of rotation.



Moment of inertia due to this segment is

$$dI = dm x^2$$

$$dI = \frac{M}{L} dx x^2$$

Total moment of inertia is given by

$$I = \int_i^f dm r^2$$

$$I = \int_{-L/2}^{+L/2} \frac{M}{L} x^2 dx$$

$$I = \frac{M}{L} \int_{-L/2}^{+L/2} x^2 dx$$

$$I = \frac{M}{L} \left[\frac{x^3}{3} \right]_{-L/2}^{+L/2}$$

$$I = \frac{M}{3L} \left[\frac{L^3}{8} + \frac{L^3}{8} \right]$$

$$I = \frac{M}{3L} \left[\frac{L^3}{4} \right]$$

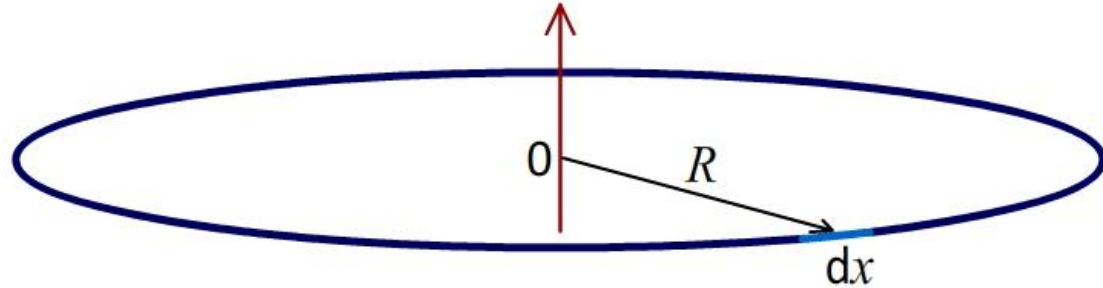
$$I = \frac{ML^2}{12}$$

System of particles and rotation

Moment of inertia of a thin ring about an axis passing through its centre and perpendicular to its plane

Let mass of the ring be M and its radius be R .

Consider a small segment of length dx . Let the mass of the segment be dm .



Moment of inertia due to this segment is

$$dI = dm R^2$$

$$dI = \frac{M}{2\pi R} dx R^2$$

$$dI = \frac{MR}{2\pi} dx$$

Total moment of inertia is given by

$$I = \int_i^f dm r^2$$

$$I = \int_0^{2\pi R} \frac{MR}{2\pi} dx$$

$$I = \frac{MR}{2\pi} \int_0^{2\pi R} dx$$

$$I = \frac{MR}{2\pi} [x]_0^{2\pi R}$$

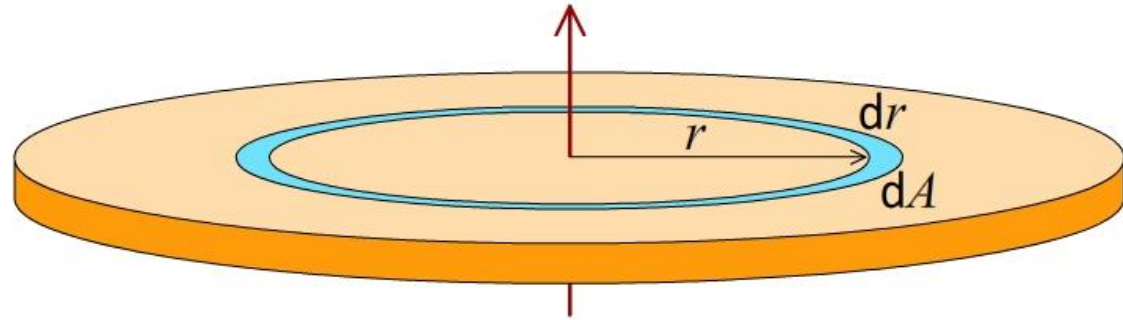
$$I = \frac{MR}{2\pi} [2\pi R]$$

$$I = MR^2$$

System of particles and rotation

Moment of inertia of a disc about an axis passing through its centre and perpendicular to its plane

Let mass of the disc be M and its radius be R and thickness t . Consider a small segment of radius r and thickness dr .



Moment of inertia due to this segment is

$$dI = dm R^2$$

$$dm = \frac{M}{V} \times dV$$

$$dI = \frac{M}{\pi R^2 t} 2\pi r dr t r^2$$

$$dI = \frac{M}{R^2} 2r dr r^2$$

Total moment of inertia is obtained by integration

$$\int dI = \int \frac{M}{R^2} 2r dr r^2$$

$$I = \frac{2M}{R^2} \int r^3 dr$$

$$I = \frac{2M}{R^2} \left[\frac{r^4}{4} \right]_0^R$$

$$I = \frac{2M}{R^2} \left[\frac{R^4}{4} - \frac{0^4}{4} \right]$$

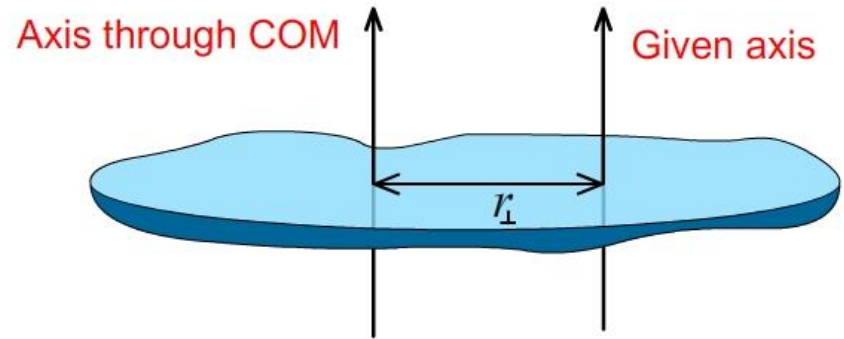
$$I = \frac{2M}{R^2} \left[\frac{R^4}{4} \right]$$

$$I = \frac{MR^2}{2}$$

Parallel axes theorem

Moment of inertia of a body about a given axis is equal to the sum of its moment of inertia about an axis passing through its centre of mass and the product of mass of the body and square of the perpendicular distance between the two axes.

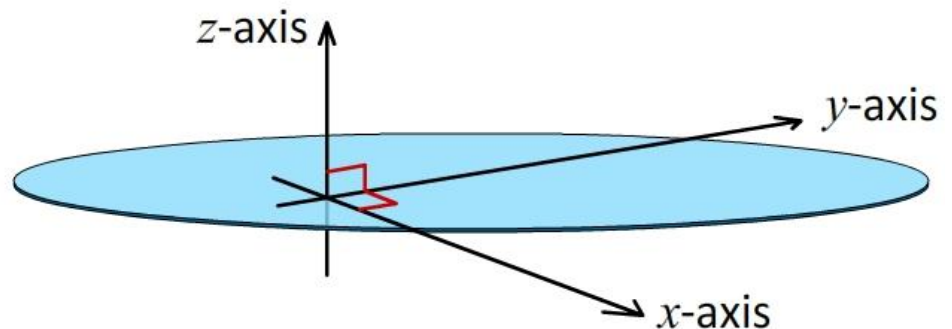
$$I_{\text{given}} = I_{\text{COM}} + MR^2$$



Perpendicular axes theorem

Moment of inertia of a plane lamina about an axis perpendicular to its plane is equal to the sum of its moments of inertia about two mutually perpendicular axes in its plane with the perpendicular axis passing through their point of intersection.

$$I_z = I_x + I_y$$



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